

Delete Relaxations for Planning with State-Dependent Action Costs

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Motivation

Cost of operator application may depend on current state:



$$\text{cost}(\text{dish washing}) = 1 \cdot |\text{plates}| + 2 \cdot |\text{glasses}| + 5 \cdot |\text{spoons}|$$

Additive Heuristic: Example

▶ $s(A) = s(B) = 0$. Question: $h_s^{add}(A = 1) = ?$

▶ Action a adds fact $A = 1$ at cost $2 - 2B$.

▶ Action b adds fact $B = 1$ at cost 1.

▶ With a : $(00) \xrightarrow{a: 2} (10)$

▶ With (b, a) : $(00) \xrightarrow{b: 1} (01) \xrightarrow{a: 0} (11) \Rightarrow \text{cheaper!}$

Action Cost Functions

Action a costs

$$c_a : \mathcal{D}_1 \times \mathcal{D}_2 \times \dots \times \mathcal{D}_k \rightarrow \mathbb{N}$$

where $\mathcal{D}_i = \{0, \dots, n_i\}$ is the domain of variable v_i on which the cost function c_a depends, $i = 1, \dots, k$.

Additive Heuristic for State-Dependent Action Costs

$$h_s^{add}(\text{fact}) = \begin{cases} 0 & \text{if } s \models \text{fact} \\ \min_{\text{achiever } a \text{ of fact}} [h_s^{add}(\text{pre}(a)) + C_s^a] & \text{otherwise,} \end{cases}$$

where $C_s^a = \min_{\hat{s} \text{ valuation of variables in } c_a} [c_a(\hat{s}) + h_s^{add}(\hat{s})]$

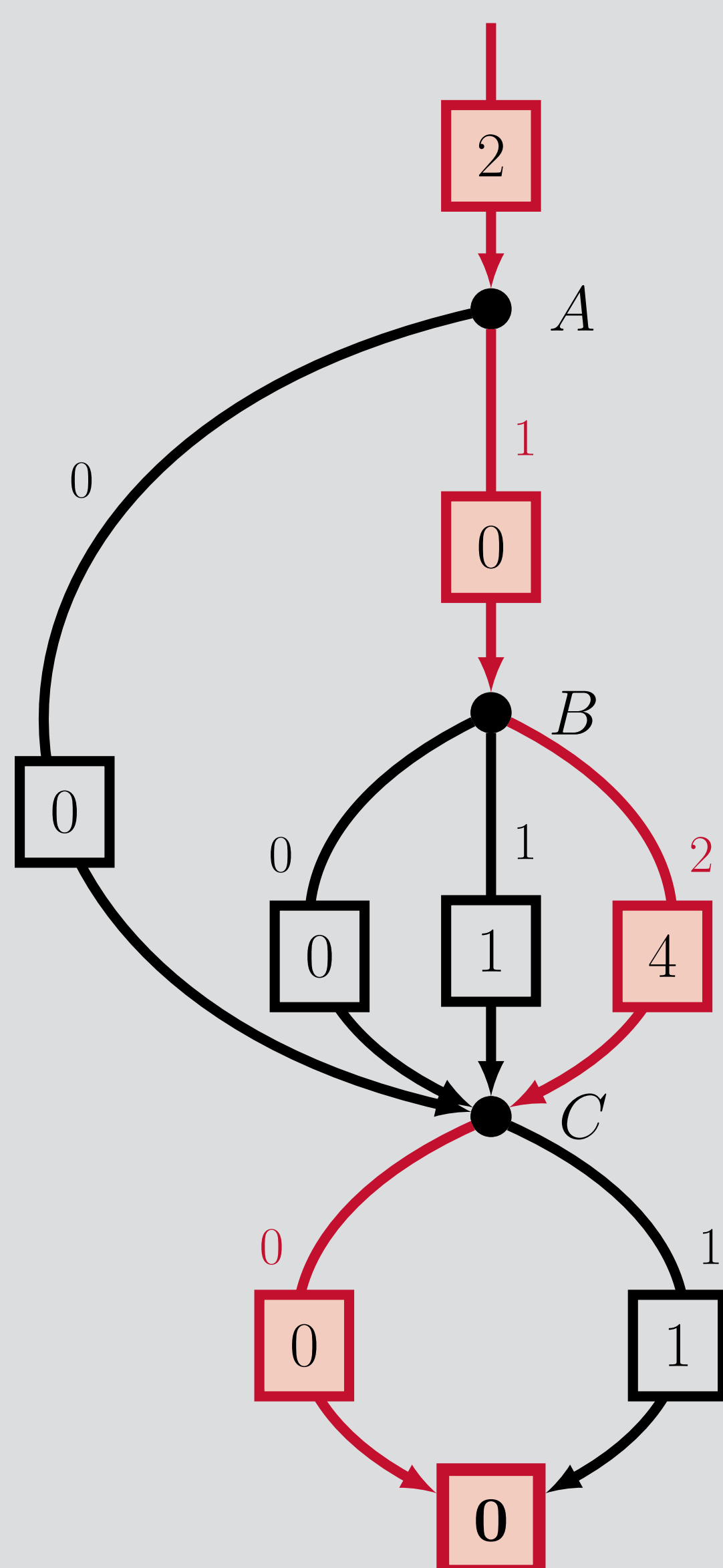
Edge-Valued Multi-Valued Decision Diagrams

Decision diagram [Ciardo & Siminiceanu, 2002] for function

$$c_a = AB^2 + C + 2$$

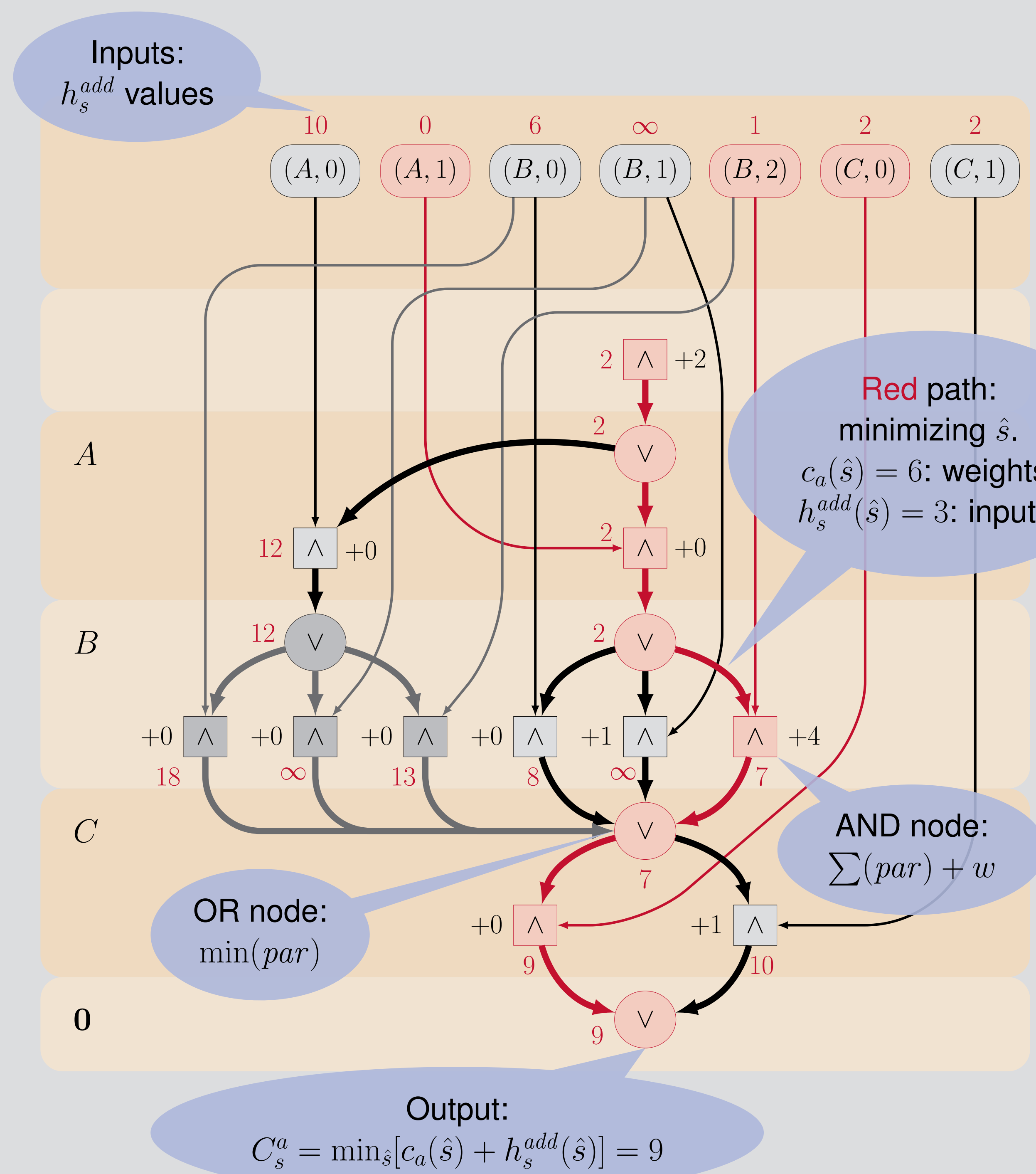
with $\mathcal{D}_A = \mathcal{D}_C = \{0, 1\}$, and $\mathcal{D}_B = \{0, 1, 2\}$

E.g., $c_a(1, 2, 0) = 2 + 0 + 4 + 0 = 6$.



Test variables on all paths.

Add inputs for facts.



Main Theoretical Result

With $h_s^{add}(\text{fact})$ values as inputs, the output of the AND/OR graph is C_s^a .

Use of the Result

- ▶ Generate AND/OR graph.
- ▶ Embed AND/OR graph in RPG.
- ▶ Compute generalized h^{add} .

Experiments

ACADEMIC ADVISING domain (IPPC 2014), PROST planner [Keller & Eyerich, 2012].

Instance	2	4	6	8	10
Variables	20	30	40	50	60
Actions	11	16	21	26	31
Variables in c_a	8	8	11	10	12
AND/OR graph	26 + 33	26 + 33	35 + 45	32 + 41	38 + 49
Plan cost IDS	46.24	202.19	202.90	201.67	201.51
Plan cost h^{add}	45.80	63.41	76.15	109.02	125.52